



Kinematics and Dynamics of Multibody Systems with Imperfect Joints: 34 (Lecture Notes in Applied and Computational Mechanics)

Paulo Flores, Jorge Ambrósio, J.C. Pimenta Claro, Hamid M. Lankarani

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This book presents suitable methodologies for the dynamic analysis of multibody mechanical systems with joints. It contains studies and case studies of real and imperfect joints. The book is intended for researchers, engineers, and graduate students in applied and computational mechanics.



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